

Exam 1 Solutions

APPM 2350, Calculus 3, Fall 2008

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1. (a) False. The range of $\sin^{-1}(x)$ with positive argument, x , is $[0, \pi/2]$. The angle, θ , can be anywhere between $[0, \pi]$ for two general vectors.
- (b) True. See definition on page 808.
- (c) False. $(\mathbf{A} \cdot \mathbf{B})$ is a scalar and therefore $(\mathbf{A} \cdot \mathbf{B}) \cdot \mathbf{C}$ only can make sense as a scalar-vector product. The same thing with $\mathbf{A} \cdot (\mathbf{B} \cdot \mathbf{C})$. Even then, the two sides are not equal.

$$\begin{aligned}(\mathbf{A} \cdot \mathbf{B}) \cdot \mathbf{C} &= (a_1b_1 + a_2b_2 + a_3b_3)(c_1\mathbf{i} + c_2\mathbf{j} + c_3\mathbf{k}) \neq \\ \mathbf{A} \cdot (\mathbf{B} \cdot \mathbf{C}) &= (b_1c_1 + b_2c_2 + b_3c_3)(a_1\mathbf{i} + a_2\mathbf{j} + a_3\mathbf{k})\end{aligned}$$

- (d) True.

$$\begin{aligned}(\mathbf{A} \times \mathbf{B}) \cdot (\mathbf{C} \times \mathbf{D}) &= (-\mathbf{B} \times \mathbf{A}) \cdot (-\mathbf{D} \times \mathbf{C}) \\ &= (-1)^2(\mathbf{B} \times \mathbf{A}) \cdot (\mathbf{D} \times \mathbf{C}) \\ &= (\mathbf{D} \times \mathbf{C}) \cdot (\mathbf{B} \times \mathbf{A})\end{aligned}$$

- (e) True. $\mathbf{A} \times \mathbf{A} = \mathbf{0}$.
- (f) True. $\mathbf{A} \times \mathbf{B}$ is orthogonal to \mathbf{A} .
- (g) True. Both sides are zero because $\mathbf{A} \times \mathbf{B}$ is orthogonal to both \mathbf{A} and \mathbf{B} .
- (h) True. By the scalar-vector product rule of derivatives:

$$\begin{aligned}\frac{d}{dt} [c^2(t)\mathbf{r}(t)] &= \frac{d}{dt}[c^2(t)]\mathbf{r}(t) + c^2(t)\frac{d}{dt}\mathbf{r}(t) \\ &= 2c'(t)c(t)\mathbf{r}(t) + c^2(t)\frac{d}{dt}\mathbf{r}(t) \\ &= c(t) \left[2c'(t)\mathbf{r}(t) + c(t)\frac{d}{dt}\mathbf{r}(t) \right]\end{aligned}$$

- (i) False. The cross product does not commute. By the cross-product rule of derivatives:

$$\frac{d}{dt} [\mathbf{r}(t) \times \mathbf{s}(t)] = \frac{d}{dt} \mathbf{r}(t) \times \mathbf{s}(t) + \mathbf{r}(t) \times \frac{d}{dt} \mathbf{s}(t)$$

- (j) False. Suppose $\mathbf{A} = \mathbf{i}$ and $\mathbf{B} = \mathbf{j}$. Then,

$$\begin{aligned} \mathbf{i} \times (\mathbf{i} \times (\mathbf{i} \times (\mathbf{i} \times \mathbf{j}))) &= \\ \mathbf{i} \times (\mathbf{i} \times (\mathbf{i} \times (\mathbf{i} \times \mathbf{k}))) &= \\ \mathbf{i} \times (\mathbf{i} \times (\mathbf{i} \times (-\mathbf{j}))) &= \\ \mathbf{i} \times (\mathbf{i} \times (-\mathbf{k})) &= \\ \mathbf{i} \times \mathbf{j} &= \mathbf{k}. \end{aligned} \tag{1}$$

2. $\mathbf{r}(t)$ is such that $|\mathbf{v}(t)| = 1$.

- (a)

$$L = \int_{t_0}^{t_1} |\mathbf{v}(t)| dt = [t]_{t_0}^{t_1} = t_1 - t_0. \tag{2}$$

- (b) Note that $|\mathbf{v}(t)|^2 = 1$. Then,

$$0 = \frac{d}{dt} (|\mathbf{v}(t)|^2) = \frac{d}{dt} (\mathbf{v}(t) \cdot \mathbf{v}(t)) = \mathbf{a}(t) \cdot \mathbf{v}(t) + \mathbf{v}(t) \cdot \mathbf{a}(t) = 2\mathbf{a}(t) \cdot \mathbf{v}(t).$$

This shows $\mathbf{a}(t) \perp \mathbf{v}(t)$.

- (c) $a_T(t) = \frac{d}{dt} |\mathbf{v}(t)| = 0$ and $a_N(t) = \sqrt{|\mathbf{a}(t)|^2 - a_T^2(t)} = |\mathbf{a}(t)|$.

3. $A(0, 0, 1)$, $B(3, 0, 0)$, and $C(0, 2, 0)$.

- (a) Vectors $\vec{AB} = 3\mathbf{i} - \mathbf{k}$ and $\vec{AC} = 2\mathbf{j} - \mathbf{k}$, so

$$\vec{AB} \times \vec{AC} = 2\mathbf{i} + 3\mathbf{j} + 6\mathbf{k}. \tag{3}$$

Let this vector be \mathbf{n} , the normal component to plane S . Then, S is written $2x + 3y + 6z = d$. Point A (or B , or C) shows $d = 6$.

- (b) $D(0, 0, 0)$, so $\vec{AD} = -\mathbf{k}$.

$$\vec{ED} = \text{proj}_{\mathbf{n}} \vec{AD} = \frac{(\vec{AD} \cdot \mathbf{n})}{|\mathbf{n}|^2} \mathbf{n} = -\frac{6}{49} (2\mathbf{i} + 3\mathbf{j} + 6\mathbf{k}) \tag{4}$$

Therefore, point E is found by moving from D up \vec{ED} backwards:

$$E \left(\frac{12}{49}, \frac{18}{49}, \frac{36}{49} \right). \quad (5)$$

An Alternate Solution: Observe a line through D in the direction of \mathbf{n} goes through plane S at the point of minimum distance, E . This line is parametrized by $x(t) = 2t$, $y(t) = 3t$, and $z(t) = 6t$. To find where this line crosses S , put the line coordinates into the plane equation and solve for t :

$$2(2t) + 3(3t) + 6(6t) = 6 \quad \implies \quad t = \frac{6}{49}. \quad (6)$$

Then, plugging t into the parameterized equations gives the same answer for E .

(c) $\vec{AF} = \text{proj}_{\vec{AB}} \vec{AD} = \frac{(\vec{AD} \cdot \vec{AB})}{|\vec{AB}|^2} \vec{AB} = \frac{1}{10}(3\mathbf{i} - \mathbf{k})$. Moving to F from A gives

$$F \left(\frac{3}{10}, 0, \frac{9}{10} \right). \quad (7)$$

An Alternate Solution: Observe that D , B , and A are all in the x - z plane. The line that goes through D that has direction orthogonal to \vec{AB} (and in the x - z plane) goes through plane S at the point of minimal distance, F . This line is parametrized by $x(t) = t$, $y(t) = 0$, and $z(t) = 3t$. Then, plug the coordinate equations of this line into the equation for S to find the point of intersection:

$$2(t) + 3(0) + 6(3t) = 6 \quad \implies \quad t = \frac{3}{10}. \quad (8)$$

Plugging t back into the coordinate equations give the same answer for F .

- (d) We know the line must go through point D , so we must find a direction for the line. The \mathbf{i} - and \mathbf{j} -components are equal, so the direction is of the form $\mathbf{w} = p\mathbf{i} + p\mathbf{j} + q\mathbf{k}$ for scalars p and q . Also the line should be moving in a plane parallel to S , or $\mathbf{w} \perp \mathbf{n}$. Simplifying,

$$\begin{aligned} (p\mathbf{i} + p\mathbf{j} + q\mathbf{k}) \cdot (2\mathbf{i} + 3\mathbf{j} + 6\mathbf{k}) &= \\ 5p + 6q &= 0. \end{aligned}$$

The length of \mathbf{w} does not matter (as long as it is not the zero vector), so we choose $q = -5$. This means that $p = 6$ (by the derived equation), and $\mathbf{w} = 6\mathbf{i} + 6\mathbf{j} - 5\mathbf{k}$. Then the line is parameterized by

$$L = \begin{cases} x(t) = 6t \\ y(t) = 6t \\ z(t) = -5t \end{cases}, \quad -\infty < t < \infty. \quad (9)$$

4. We start by computing the acceleration and velocity:

$$\begin{aligned}\mathbf{r}(t) &= (2t + 3)\mathbf{i} + (5 - t^2)\mathbf{j} \\ \mathbf{v}(t) &= \quad \quad 2\mathbf{i} \quad \quad -2t\mathbf{j} \\ \mathbf{a}(t) &= \quad \quad \quad \quad \quad -2\mathbf{j}\end{aligned}\tag{10}$$

$$\hat{\mathbf{T}} = \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{1}{\sqrt{1+t^2}}(\mathbf{i} - t\mathbf{j})\tag{11}$$

We know that $\hat{\mathbf{B}} = -\mathbf{k}$ and torsion $\tau = 0$ because this is a clock-wise moving curve in the x - y plane.

$$\hat{\mathbf{N}} = \hat{\mathbf{B}} \times \hat{\mathbf{T}} = \frac{1}{\sqrt{1+t^2}}(-t\mathbf{i} - \mathbf{j}).\tag{12}$$

$$\kappa = \frac{|\mathbf{v}(t) \times \mathbf{a}(t)|}{|\mathbf{v}(t)|^3} = \frac{4}{(4 + 4t^2)^{3/2}} = \frac{1}{2(1 + t^2)^{3/2}}.\tag{13}$$

5. (a) This is a one-variable limit, so we may use L'Hopital's rule (\Rightarrow):

$$\frac{1 - \cos x}{\tan^2 x} \xrightarrow[L'H.]{\implies} \frac{\sin x}{2 \tan x \sec^2 x} = \frac{\cos^3 x}{2} \longrightarrow \frac{1}{2} \quad \text{as } x \rightarrow 0.\tag{14}$$

(b) Move to $(0, 0)$ along line $y = kx$ for some k :

$$\frac{(x + y)^2}{x^2 + y^2} = \frac{(x + kx)^2}{x^2 + k^2x^2} = \frac{(1 + k)^2x^2}{(1 + k^2)x^2} = \frac{1 + 2k + k^2}{1 + k^2}.\tag{15}$$

If $k = 0$, then the function goes to 1 as $(x, y) \rightarrow (0, 0)$. For $k = 1$, the function goes to 2. The function approaches different values for different paths through $(0, 0)$ so the limit does not exist by the *the two-path test* (see pg. 920).

(c) The top can be factored and one term cancels with the bottom:

$$\frac{xy + x + 2y + 2}{y + 1} = \frac{(y + 1)(x + 2)}{y + 1} \longrightarrow 3 \quad \text{as } (x, y) \rightarrow (1, -1).\tag{16}$$