

Solutions, Exam 3, Spring 2001

1. $Ax=0$ has non-trivial solutions $\Leftrightarrow \det(A)=0$

$$\begin{vmatrix} a & 1 & \frac{3}{2} \\ -2 & a & 0 \\ 0 & a & 1 \end{vmatrix} = -a \begin{vmatrix} a & \frac{3}{2} \\ -2 & 0 \end{vmatrix} + \begin{vmatrix} a & 1 \\ -2 & a \end{vmatrix} = -3a + a^2 + 2$$

$$a^2 - 3a + 2 = 0 \Leftrightarrow a = \frac{3}{2} \pm \sqrt{\frac{9}{4} - \frac{8}{4}} = \frac{3}{2} \pm \frac{1}{2}$$

$$\boxed{a=2 \text{ or } a=1}$$

Alternative solution:

Perform Gaussian elimination on $Ax=0$

$$\left(\begin{array}{ccc|c} a & 1 & \frac{3}{2} & 0 \\ -2 & a & 0 & 0 \\ 0 & a & 1 & 0 \end{array} \right) \begin{array}{l} \updownarrow \\ \updownarrow \end{array} \left(\begin{array}{ccc|c} -2 & a & 0 & 0 \\ a & 1 & \frac{3}{2} & 0 \\ 0 & a & 1 & 0 \end{array} \right) \begin{array}{l} \left(\frac{a}{2}\right) \\ \leftarrow \end{array}$$

$$\left(\begin{array}{ccc|c} -2 & a & 0 & 0 \\ 0 & 1 + \frac{a^2}{2} & \frac{3}{2} & 0 \\ 0 & a & 1 & 0 \end{array} \right) \begin{array}{l} \left(\frac{-a}{1 + \frac{a^2}{2}}\right) \\ \leftarrow \end{array} \left(\begin{array}{ccc|c} -2 & a & 0 & 0 \\ 0 & 1 + \frac{a^2}{2} & \frac{3}{2} & 0 \\ 0 & 0 & 1 - \frac{3/2 a}{1 + \frac{a^2}{2}} & 0 \end{array} \right)$$

There can be a nonzero solution only if

$$1 - \frac{3/2 a}{1 + \frac{a^2}{2}} = 0 \Leftrightarrow 1 + \frac{a^2}{2} - \frac{3}{2} a = 0 \Leftrightarrow$$

$$a^2 - 3a + 2 = 0 \Rightarrow$$

$$\boxed{a=2 \text{ or } a=1}$$

2. To solve $\bar{x}' = A\bar{x}$, find eigenvalues and eigenvectors.

a) $A = \begin{pmatrix} 2 & 5 \\ -2 & 0 \end{pmatrix}$

$$p(\lambda) = \det(A - \lambda I) = \begin{vmatrix} 2-\lambda & 5 \\ -2 & -\lambda \end{vmatrix} = \lambda^2 - 2\lambda + 10$$

$$\lambda^2 - 2\lambda + 10 = 0 \Leftrightarrow \lambda = 1 \pm \sqrt{1-10} = 1 \pm 3i$$

$$\Rightarrow \boxed{\lambda_1 = 1 + 3i \quad \lambda_2 = 1 - 3i}$$

$$\underline{\lambda_1 = 1 + 3i}: \quad \left(\begin{array}{cc|c} 1-3i & 5 & 0 \\ -2 & -1-3i & 0 \end{array} \right) \xrightarrow{\frac{1+3i}{5}} \left(\begin{array}{cc|c} 1-3i & 5 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

$$\text{Let } v_2 = s \Rightarrow (1-3i)v_1 + 5s = 0 \Leftrightarrow$$

$$v_1 = -\frac{5}{1-3i} s = -\frac{5(1+3i)}{10} s = \left(-\frac{1}{2} - \frac{3}{2}i\right) s$$

$$\bar{v} = \begin{pmatrix} -\frac{1}{2} - \frac{3}{2}i \\ 1 \end{pmatrix} s \quad \text{Choose for ex. } \bar{v}_1 = \begin{pmatrix} 1+3i \\ -2 \end{pmatrix}$$

The second eigenvector \bar{v}_2 is the complex conjugate of \bar{v}_1

$$\Rightarrow \boxed{\bar{v}_1 = \begin{pmatrix} 1+3i \\ -2 \end{pmatrix} \quad \bar{v}_2 = \begin{pmatrix} 1-3i \\ -2 \end{pmatrix}}$$

2 contd. Find the real valued solutions from the complex valued solution $z = \bar{v}_1 e^{\lambda_1 t}$

$$\begin{aligned} z &= \begin{pmatrix} 1+3i \\ -2 \end{pmatrix} e^{(1+3i)t} = \left(\begin{pmatrix} 1 \\ -2 \end{pmatrix} + i \begin{pmatrix} 3 \\ 0 \end{pmatrix} \right) e^t (\cos 3t + i \sin 3t) = \\ &= \begin{pmatrix} 1 \\ -2 \end{pmatrix} e^t \cos 3t - \begin{pmatrix} 3 \\ 0 \end{pmatrix} e^t \sin 3t + i \left[\begin{pmatrix} 1 \\ -2 \end{pmatrix} e^t \sin 3t + \begin{pmatrix} 3 \\ 0 \end{pmatrix} e^t \cos 3t \right] \end{aligned}$$

$$\bar{x}_1 = \operatorname{Re}(z) = \begin{pmatrix} e^t (\cos 3t - 3 \sin 3t) \\ -2 e^t \cos 3t \end{pmatrix}$$

$$\bar{x}_2 = \operatorname{Im}(z) = \begin{pmatrix} e^t (\sin 3t + 3 \cos 3t) \\ -2 e^t \sin 3t \end{pmatrix}$$

General solution :

$$\bar{x}(t) = c_1 \bar{x}_1 + c_2 \bar{x}_2 =$$

$$= c_1 \begin{pmatrix} e^t (\cos 3t - 3 \sin 3t) \\ -2 e^t \cos 3t \end{pmatrix} + c_2 \begin{pmatrix} e^t (\sin 3t + 3 \cos 3t) \\ -2 e^t \sin 3t \end{pmatrix}$$

$$2b) \quad A = \begin{pmatrix} 3 & 1 \\ -1 & 1 \end{pmatrix}$$

$$p(\lambda) = \det(A - \lambda I) = \begin{vmatrix} 3-\lambda & 1 \\ -1 & 1-\lambda \end{vmatrix} = (3-\lambda)(1-\lambda) + 1 = \\ = \lambda^2 - 4\lambda + 4$$

$$\lambda^2 - 4\lambda + 4 = 0 \Leftrightarrow \lambda = 2 \pm \sqrt{4-4} = 2$$

$$\Rightarrow \boxed{\lambda_1 = 2, \lambda_2 = 2}$$

$$\underline{\lambda = 2}: \quad \begin{pmatrix} 1 & 1 & | & 0 \\ -1 & -1 & | & 0 \end{pmatrix} \begin{matrix} \textcircled{1} \\ \leftarrow \end{matrix} \begin{pmatrix} 1 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{pmatrix}$$

$$\text{Let } v_2 = s \Rightarrow v_1 + s = 0 \Rightarrow v_1 = -s$$

$$\bar{v} = \begin{pmatrix} -1 \\ 1 \end{pmatrix} s \quad \text{Choose } \boxed{\bar{v}_1 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}}$$

Only one eigenvector, deficient eigenspace

Find generalized eigenvector

$$(A - 2I)\bar{u} = \bar{v}_1 \Leftrightarrow \begin{pmatrix} 1 & 1 & | & -1 \\ -1 & -1 & | & 1 \end{pmatrix} \begin{matrix} \textcircled{1} \\ \leftarrow \end{matrix} \begin{pmatrix} 1 & 1 & | & -1 \\ 0 & 0 & | & 0 \end{pmatrix}$$

$$\text{Let } u_2 = s \Rightarrow u_1 + s = -1 \Rightarrow u_1 = -1 - s$$

$$\bar{u} = \begin{pmatrix} -1 \\ 0 \end{pmatrix} + \begin{pmatrix} -1 \\ 1 \end{pmatrix} s \quad \text{Choose } \boxed{\bar{u} = \begin{pmatrix} -1 \\ 0 \end{pmatrix}}$$

$$\bar{x}_1 = \bar{v}_1 e^{\lambda t} = \begin{pmatrix} -1 \\ 1 \end{pmatrix} e^{2t} \quad \bar{x}_2 = (\bar{u} + t\bar{v}_1) e^{\lambda t} = \left(\begin{pmatrix} -1 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ 1 \end{pmatrix} \right) e^{2t}$$

$$\text{Gen. sol. } \boxed{\bar{x}(t) = c_1 \bar{x}_1 + c_2 \bar{x}_2 = c_1 \begin{pmatrix} -1 \\ 1 \end{pmatrix} e^{2t} + c_2 \begin{pmatrix} -1-t \\ t \end{pmatrix} e^{2t}}$$

2c, For both a_j and b_j both eigenvalues
have a positive real part
 \Rightarrow hyperbolic source

$$3. \begin{cases} x' = \sin(x+y) \\ y' = (x-1)^2 + y^2 - 1 \end{cases}$$

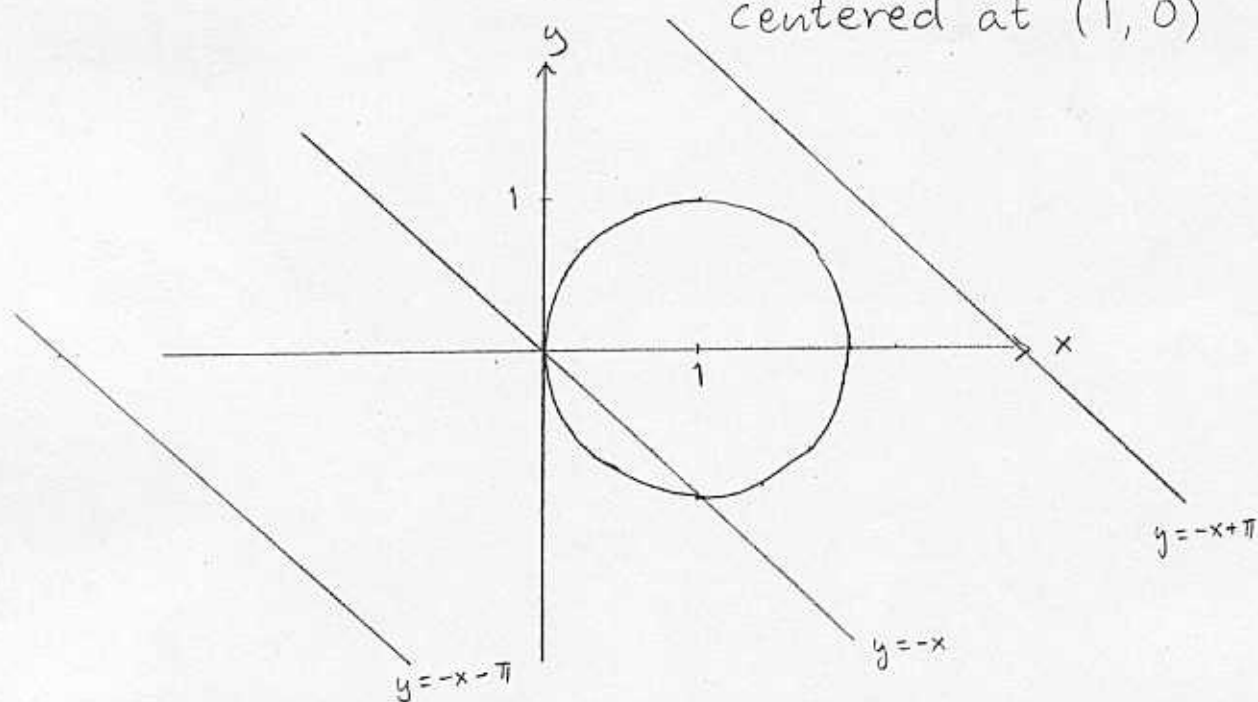
a) Find the two equilibrium points

$$0 = \sin(x+y) \quad (1)$$

$$0 = (x-1)^2 + y^2 - 1 \quad (2)$$

$$(1) \Rightarrow x+y = n\pi \Leftrightarrow y = -x + n\pi$$

$$(2) \Rightarrow (x-1)^2 + y^2 = 1 \quad \text{Circle of radius one centered at } (1, 0)$$



The equilibria are found for $y = -x$

$$\text{Insert into (2)} \Rightarrow (x-1)^2 + x^2 - 1 = 0$$

$$\Leftrightarrow 2x^2 - 2x = 0 \Leftrightarrow 2x(x-1) = 0$$

$$\Rightarrow x = 0 \quad \text{or} \quad x = 1$$

Equilibria $(0, 0)$ and $(1, -1)$

3a, Alternative solution:

$$0 = \sin(x+y) \quad (1)$$

$$0 = (x-1)^2 + y^2 - 1 \quad (2)$$

$$(1) \Rightarrow x+y = n\pi \Leftrightarrow y = -x + n\pi$$

Insert into (2)

$$x^2 - 2x + 1 + x^2 - 2xn\pi + n^2\pi^2 - 1 = 0 \Leftrightarrow$$

$$2x^2 - (1+n\pi)2x + n^2\pi^2 = 0 \Leftrightarrow$$

$$x^2 - (1+n\pi)x + \frac{n^2\pi^2}{2} = 0 \Leftrightarrow$$

$$x = \frac{1+n\pi}{2} \pm \sqrt{\frac{1+2n\pi+n^2\pi^2}{4} - \frac{2n^2\pi^2}{4}} \Leftrightarrow$$

$$x = \frac{1+n\pi}{2} \pm \frac{\sqrt{1+2n\pi-n^2\pi^2}}{2}$$

Real solutions if $1+2n\pi \geq n^2\pi^2$

True for $n=0$ only

$$\Rightarrow x = \frac{1}{2} \pm \frac{1}{2}$$

$$\Rightarrow x=1 \text{ and } x=0$$

Equilibria $(0,0)$ and $(1,-1)$

36, Linearize around $(0,0)$ (No shift needed)

$$\begin{cases} x' = \sin(x+y) = f(x,y) \\ y' = (x-1)^2 + y^2 - 1 = g(x,y) \end{cases}$$

$$J(x,y) = \begin{pmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{pmatrix} = \begin{pmatrix} \cos(x+y) & \cos(x+y) \\ 2x-2 & 2y \end{pmatrix}$$

$$J(0,0) = \begin{pmatrix} 1 & 1 \\ -2 & 0 \end{pmatrix}$$

Linearized system $\boxed{\bar{x}' = \begin{pmatrix} 1 & 1 \\ -2 & 0 \end{pmatrix} \bar{x}}$

or

Linearize around $(1, -1)$. Needs shifting

Let $\bar{u} = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} - \begin{pmatrix} 1 \\ -1 \end{pmatrix} \Rightarrow \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} + \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} u_1 + 1 \\ u_2 - 1 \end{pmatrix}$

$$\begin{cases} u_1' = \sin(u_1 + u_2) = f(u_1, u_2) \\ u_2' = u_1^2 + (u_2 - 1)^2 - 1 = g(u_1, u_2) \end{cases}$$

$$J(x,y) = \begin{pmatrix} \frac{\partial f}{\partial u_1} & \frac{\partial f}{\partial u_2} \\ \frac{\partial g}{\partial u_1} & \frac{\partial g}{\partial u_2} \end{pmatrix} = \begin{pmatrix} \cos(u_1 + u_2) & \cos(u_1 + u_2) \\ 2u_1 & 2u_2 - 2 \end{pmatrix}$$

$$J(0,0) = \begin{pmatrix} 1 & 1 \\ 0 & -2 \end{pmatrix}$$

Linearized system $\boxed{\bar{u}' = \begin{pmatrix} 1 & 1 \\ 0 & -2 \end{pmatrix} \bar{u}}$

4.

	True	False
a		F
b		F
c		F
d	T	
e		F