

1. a. Separable:  $\frac{y'}{y^2} = 1$ , Integrate:  $-\frac{1}{y} = t + C$ ,  
 $y = -\frac{1}{t+C}$  .  $y(0) = 1 \Rightarrow C = -1 \Rightarrow y(t) = \frac{1}{1-t}$ ,

This solution becomes infinite for  $t = 1$ ,

b. Write the DE  $y' - \frac{y}{t} = 1$ , i.e. the integrating factor is  $e^{-\int \frac{dt}{t}} = e^{-\ln t} = e^{\ln \frac{1}{t}} = \frac{1}{t}$ . Therefore

$$\frac{d}{dt} \left( \frac{1}{t} \cdot y \right) = \frac{1}{t}, \quad \frac{1}{t} y = \ln|t| + C,$$

From  $y(1) = 1$  follows  $C = 1$ .

$$\Rightarrow y = t \ln|t| + t,$$

Solution is valid only down to  $t = 0$ ,

So it is  $y = t \ln t + t$  for  $t > 0$ .

c. We recognize the DE as a Bernoulli equation, with  $\alpha = 3$ . Therefore, set  $u = y^{1-3} = \frac{1}{y^2} \Rightarrow$

$$y = u^{-1/2}, \quad y' = -\frac{1}{2} u^{-3/2} u'$$

Plug into the DE:

$$-\frac{1}{2} u^{-3/2} u' = \frac{u^{-1/2}}{t} + u^{-3/2}$$

which simplifies to

$$u' + \frac{2}{t} u = -2$$

Integrating factor  $e^{2 \int \frac{dt}{t}} = e^{2 \ln t} = e^{\ln t^2} = t^2$ .

$$\Rightarrow \frac{d}{dt} (t^2 u) = -2t^2 \Rightarrow t^2 u = -\frac{2}{3} t^3 + C,$$

$$u = -\frac{2}{3} t + \frac{C}{t^2}$$

$$y(1) = \sqrt{3} \Rightarrow u(1) = \frac{1}{3} \Rightarrow c = 1.$$

②

$$\text{Therefore } y(t) = \frac{1}{\sqrt{u(t)}} = \frac{1}{\sqrt{\frac{1}{t^2} - \frac{2}{3}t}} = \frac{\sqrt{3}t}{\sqrt{3-2t^3}}$$

---

2. a. According to Newton's law of cooling, the tea temperature will obey

$$\begin{cases} T'(t) = k(30 - T(t)) \\ T(0) = 90, T(1) = 60. \end{cases}$$

b. We write the DE

$$T' + kT = 30k \quad ; \quad \text{Integrating factor } e^{kt} :$$

$$\Rightarrow \frac{d}{dt} (e^{kt} T) = 30k e^{kt}$$

$$\Rightarrow T(t) = 30 + C \cdot e^{-kt}$$

$$T(0) = 90 \Rightarrow C = 60$$

$$T(1) = 60 \Rightarrow C \cdot e^{-k} = 30 ; e^{-k} = \frac{1}{2}$$

The temperature at time  $t$  will therefore

$$\text{be } T(t) = 30 + 60 \cdot 2^{-t}.$$

---

3. a, 
$$\left[ \begin{array}{ccc|c} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -1 & 3 \end{array} \right] \sim \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 1 \\ 0 & -2 & 0 & -2 \\ 0 & 0 & -2 & 2 \end{array} \right]$$
 Eliminate using row 1.

We can immediately read off  $z = -1, y = 1$ ; then top row tells  $x = 1$ .

b, The elimination we just did did not change the value of the determinant. For an upper triangular matrix, it is the product of the diagonal elements.  $\Rightarrow \det = 4$ .

c, 
$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ -1 & 1 & 0 & 1 \\ 3 & -1 & 1 & -1 \end{bmatrix}$$

Elimination to RREF gives

$$A \sim \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 2 & -1 & 2 \\ 0 & -4 & -2 & -4 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & -1/2 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1/2 & 1 \\ 0 & 1 & -1/2 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The first two columns contain pivot entries. Therefore, the first two columns of  $A$  can be used for a base of the column space (dimension 2).

4.  $A = \frac{1}{3} \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}$

(4)

a.  $\frac{1}{3} \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ . So  $\lambda_1 = 0$ .

b.  $(A - \lambda I) \begin{bmatrix} v \\ v \\ v \end{bmatrix} = \frac{1}{3} \begin{bmatrix} -1 & -1 & -1 \\ -1 & -1 & -1 \\ -1 & -1 & -1 \end{bmatrix} \begin{bmatrix} v \\ v \\ v \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

So we get

$v_1 + v_2 + v_3 = 0$  three lines:

This is solved for ex by

$\begin{bmatrix} v \\ v \\ v \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} v \\ v \\ v \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$ .

c. Part (a) showed that the matrix  $A$  is singular. So its determinant is therefore zero.

5. a. We guess  $y = Ae^{-2t}$ .

Substituting into the DE gives

$4Ae^{-2t} - Ae^{-2t} = e^{-2t}$

$3A = 1, A = \frac{1}{3}$

Therefore  $y_p = \frac{1}{3}e^{-2t}$ .

b. Homogeneous equation  $y'' - y = 0$

$$r^2 - 1 = 0 \Rightarrow r = \pm 1.$$

So

$$y_1(t) = e^t, \quad y_2(t) = e^{-t}$$

$$W(y_1, y_2) = \begin{vmatrix} e^t & e^{-t} \\ e^t & -e^{-t} \end{vmatrix} = -1 - 1 = -2$$

$$y_p = v_1(t)y_1(t) + v_2(t)y_2(t)$$

where (standard formula)

$$v_1' = -\frac{e^{-t} \cdot e^{-2t}}{-2} = \frac{1}{2}e^{-3t}; \quad v_1(t) = -\frac{1}{6}e^{-3t}$$

$$v_2' = \frac{e^t \cdot e^{-2t}}{-2} = -\frac{1}{2}e^{-t}; \quad v_2(t) = \frac{1}{2}e^{-t}$$

and

$$y_p = -\frac{1}{6}e^{-3t}e^t + \frac{1}{2}e^{-t}e^{-t} = \left(-\frac{1}{6} + \frac{1}{2}\right)e^{-2t} = \frac{1}{3}e^{-2t}$$

b x-nullclines:  $x = \pm 1, y = 0$

y-nullclines:  $y = \pm 1, x + \frac{3}{10}y = 0$

a)

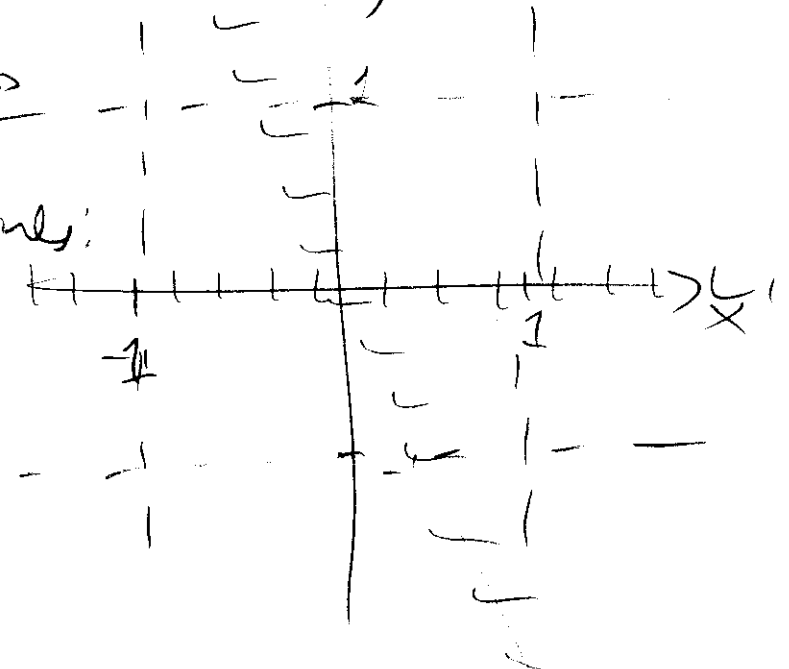
So equilibrium points at all intersections

of different nullclines:

$(1, 1), (1, -1), (-1, 1), (-1, -1)$

$(0, 0)$

$(-1, \frac{10}{3}), (1, -\frac{10}{3})$



6

b, locally at origin, can ignore quadratic terms. So

$$\begin{pmatrix} x \\ y \end{pmatrix}' = \begin{pmatrix} 0 & -1 \\ 1 & \frac{3}{10} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

Eig. values:

$$0 = |A - \lambda I| = \begin{vmatrix} -\lambda & -1 \\ 1 & \frac{3}{10} - \lambda \end{vmatrix} = \lambda^2 - \frac{3}{10}\lambda + 1 = 0$$

$$\lambda_{1,2} = \frac{3}{20} \pm \sqrt{\frac{9}{400} - 1}$$

So complex, real part  $> 0 \Rightarrow$  spiral out.

For direction, check direction of arrow, for ex.

$y=0, x < 1$ ; Then  $x'=0, y' > 0$ . So

counterclockwise.

- 7,
- a-5
  - b-4
  - c-2
  - d-3
  - e-6
  - f-1.

8. Multiple choice - for each question, mark below by a cross either True or False (i.e. not always correct). Each of the 20 questions is worth 1 point, and there is a 5 point bonus if you get them all correct. You need not give any explanations.

		<u>True</u>	<u>False</u>
a.	The DE $y' = t + y$ is separable	<input type="checkbox"/>	<input checked="" type="checkbox"/>
b.	The DE $y' + \sqrt{t}y = e^{-3t}$ is linear	<input checked="" type="checkbox"/>	<input type="checkbox"/>
c.	The DE $y' - y = y^3$ is a Bernoulli equation	<input checked="" type="checkbox"/>	<input type="checkbox"/>
d.	If the rows of a matrix are linearly independent, so are the columns	<input type="checkbox"/>	<input checked="" type="checkbox"/>
e.	It holds that $\frac{a+ib}{c+id} = \frac{(ac+bd) - i(bc+ad)}{c^2+d^2}$	<input type="checkbox"/>	<input checked="" type="checkbox"/>
f.	A quadratic equation $x^2 + ax + b = 0$ with real coefficients can have a double root that is not real	<input type="checkbox"/>	<input checked="" type="checkbox"/>
g.	If the eigenvalues to a real matrix are complex, so are the eigenvectors	<input checked="" type="checkbox"/>	<input type="checkbox"/>
h.	The system $\begin{cases} x' = xy \\ y' = 1 - x^2 - y^2 \end{cases}$ has five equilibrium points	<input type="checkbox"/>	<input checked="" type="checkbox"/>
i.	The matrix $\begin{bmatrix} 3 & -1 \\ 1 & 1 \end{bmatrix}$ has two independent eigenvectors	<input type="checkbox"/>	<input checked="" type="checkbox"/>
j.	The matrix in problem 8i above is singular	<input type="checkbox"/>	<input checked="" type="checkbox"/>
k.	All solutions to $y'' + 4y = \cos 2t$ grow unbounded with time	<input checked="" type="checkbox"/>	<input type="checkbox"/>
l.	$\begin{vmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 1 & 0 \end{vmatrix} = 1$	<input type="checkbox"/>	<input checked="" type="checkbox"/>
m.	If $A$ and $B$ are square matrices, then $(AB)^T = A^T B^T$	<input type="checkbox"/>	<input checked="" type="checkbox"/>
n.	If $ b  > 1$ , then solutions to $y' - by = 0$ grow with time	<input type="checkbox"/>	<input checked="" type="checkbox"/>
o.	The solutions to $y' = -t/y$ form circles in the $(t,y)$ -plane	<input checked="" type="checkbox"/>	<input type="checkbox"/>
p.	The integrating factor for $y' + y = \frac{1}{1+e^t}$ is $e^t$	<input checked="" type="checkbox"/>	<input type="checkbox"/>
q.	$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$	<input type="checkbox"/>	<input checked="" type="checkbox"/>
r.	If $A$ is invertible (non-singular), the linear system $Ax = b$ has a unique solution	<input checked="" type="checkbox"/>	<input type="checkbox"/>
s.	Vectors that form a base are always linearly independent	<input checked="" type="checkbox"/>	<input type="checkbox"/>
t.	$\begin{bmatrix} 1 \\ i \end{bmatrix}$ is an eigenvector to the matrix $\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$	<input checked="" type="checkbox"/>	<input type="checkbox"/>