

SECTION 4.5 - VARIATION OF PARAMETERS

D.E. 4.5a

Suppose that we seek a particular solⁿ to the eqⁿ

$$y'' + y = \frac{1}{\cos(t)} \quad \text{for } -\frac{\pi}{2} < t < \frac{\pi}{2}.$$

The methods described so far do not help.

A particular solⁿ is $y_p = \cos(t) \log(\cos(t)) + t \sin(t)$.

How could you possibly find this !?!?

The answer is a method called "variation of parameters".

Basic idea: Find the general solⁿ to the homogeneous eqⁿ and then look for a particular solⁿ by "perturbing" it.

To be specific, let p & q be functions and consider the eqⁿ

$$y'' + p y' + q y = f \quad (\text{ODE})$$

Suppose y_1 & y_2 are linearly independent solⁿs of

$$y'' + p y' + q y = f. \quad (\text{HOM})$$

In other words, $\{y_1, y_2\}$ is a basis for the solⁿ space of the homogeneous eqⁿ.

Now, somewhat arbitrarily, we look for a particular solⁿ of the form

$$y_p(t) = v_1(t) y_1(t) + v_2(t) y_2(t) \quad (\text{ANSATZ})$$

where $v_1 = v_1(t)$ & $v_2 = v_2(t)$ are two functions to be determined.

By plugging y_p into (ODE), we get one eqⁿ for y_p ,
but this is not enough since we've got two unknown functions.

We add an "ad hoc" equation

$$v_1' y_1 + v_2' y_2 = 0. \quad (1)$$

Time to start calculating...

From (ANSATZ), we get

$$y_p' = \underbrace{v_1' y_1 + v_2' y_2}_{=0 \text{ by (1)}} + v_1 y_1' + v_2 y_2' = v_1 y_1' + v_2 y_2' \quad (2)$$

$$y_p'' = v_1' y_1' + v_2' y_2' + v_1 y_1'' + v_2 y_2'' \quad (3)$$

Insert (2) & (3) into (ODE):

$$\underbrace{v_1' y_1' + v_2' y_2' + v_1 y_1'' + v_2 y_2''}_{= y_p''} + \underbrace{p v_1 y_1' + p v_2 y_2'}_{= p y_p'} + \underbrace{q v_1 y_1 + q v_2 y_2}_{= q y_p} = f \Rightarrow$$

$$\Rightarrow v_1' y_1' + v_2' y_2' + \underbrace{v_1 (y_1'' + p y_1' + q y_1)}_{=0 \text{ since } y_1 \text{ solves (Hom)}} + \underbrace{v_2 (y_2'' + p y_2' + q y_2)}_{=0 \text{ since } y_2 \text{ solves (Hom)}} = f$$

To summarize: From (ODE), we obtained the condⁿ

$$v_1' y_1' + v_2' y_2' = f \quad (4).$$

We write (1) & (4) as a system for v_1' & v_2' :

$$\begin{cases} y_1' v_1' + y_2' v_2' = f \\ y_1 v_1' + y_2 v_2' = 0 \end{cases} \Leftrightarrow \begin{bmatrix} y_1 & y_2 \\ y_1' & y_2' \end{bmatrix} \begin{bmatrix} v_1' \\ v_2' \end{bmatrix} = \begin{bmatrix} 0 \\ f \end{bmatrix}$$

Use the formula for the inverse of a 2x2 matrix, with $W(t) = \det \begin{bmatrix} y_1 & y_2 \\ y_1' & y_2' \end{bmatrix}$ \leftarrow Wronskian of $\{y_1, y_2\}$!

$$\begin{bmatrix} v_1' \\ v_2' \end{bmatrix} = \frac{1}{W(t)} \begin{bmatrix} y_2' & -y_2 \\ -y_1' & y_1 \end{bmatrix} \begin{bmatrix} 0 \\ f \end{bmatrix}$$

So $v_1' = -\frac{y_2 f}{W}$ and $v_2' = \frac{y_1 f}{W}$

Now simply integrate to find v_1 and v_2 !

Let us summarize our procedure for finding a particular solⁿ to $y'' + py' + qy = f$:

- Step 1: Find two independent sol^{ns} y_1 and y_2 of the homogeneous eqⁿ $y'' + py' + qy = 0$
- Step 2: Compute the Wronskian $W(t) = y_1 y_2' - y_1' y_2$
- Step 3: Integrate the equations $\begin{cases} v_1' = -\frac{y_2 f}{W} \\ v_2' = \frac{y_1 f}{W} \end{cases}$ to obtain v_1 and v_2 .
- Step 4: Aggregate the solⁿ $y_p = v_1 y_1 + v_2 y_2$

Remarks * If you are given an eqⁿ of the form

$$r(t)y''(t) + p(t)y'(t) + q(t)y(t) = f(t),$$

then start by ~~re~~ dividing by $r(t)$!

$$y''(t) + \frac{p(t)}{r(t)}y'(t) + \frac{q(t)}{r(t)}y(t) = \frac{f(t)}{r(t)}$$

* Note that $W(t) \neq 0$ since $\{y_1, y_2\}$ is a linearly independent set of sol^{ns} to an ODE. (Recall that whereas for a general set of functions it is not the case that linear independence implies non-zero Wronskian, this is the case when all functions solve a joint ODE.)

* When integrating the eq^{ns}

$$\frac{y_1' - y_2'}{y_1 y_2} = \frac{f}{W} \quad v_1' = -\frac{y_2 f}{W} \quad \text{and} \quad v_2' = \frac{y_1 f}{W}$$

there is no need to include general integration constants - any solⁿ will do. (This is similar to the "integrating factor" situation.)

Example $y'' + y = \frac{1}{\cos t}$ $|t| < \pi/2$

$$r^2 + 1 = 0 \Rightarrow r = \pm i \Rightarrow y_1 = \cos(t) \quad y_2 = \sin(t)$$

$$W = \begin{vmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{vmatrix} = \cos^2(t) + \sin^2(t) = 1$$

$$V_1' = -\frac{y_2 f}{W} = -\frac{\sin(t) \cdot \frac{1}{\cos(t)}}{1} = -\tan(t) \Rightarrow V_1 = \log(\cos(t))$$

$$V_2' = \frac{y_1 f}{W} = \frac{\cos(t) \cdot \frac{1}{\cos(t)}}{1} = 1 \Rightarrow V_2 = t$$

$$y_p = V_1 y_1 + V_2 y_2 = \cos(t) \log(\cos(t)) + t \sin(t)$$

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$$t^2 y'' - 2ty' + 2y = t^3 \sin(t)$$

$$y_1 = t \quad y_2 = t^2$$

$$y'' - \frac{2}{t}y' + \frac{2}{t^2}y = t \sin(t) \quad f = t \sin(t)$$

$$W = \begin{vmatrix} t & t^2 \\ 1 & 2t \end{vmatrix} = 2t^2 - t^2 = t^2$$

$$V_1' = -\frac{y_2 f}{W} = -\frac{t^2 t \sin(t)}{t^2} = -t \sin(t)$$

$$V_1 = -\int t \sin(t) dt = t \cos(t) - \int \sin(t) dt = t \cos(t) + \sin(t)$$

$$V_2' = \frac{y_1 f}{W} = \frac{t t \sin(t)}{t^2} = \sin(t) \Rightarrow V_2 = -\cos(t)$$

$$y_p = V_1 y_1 + V_2 y_2 = t^2 \cos(t) + t \sin(t) - t^2 \cos(t) = t \sin(t)$$

check:

$$y' = \sin(t) + t \cos(t)$$

$$y'' = \cos(t) + \cos(t) - t \sin(t) = 2 \cos(t) - t \sin(t)$$

$$t^2 y'' - 2ty' + 2y = 2t^2 \cos(t) - t^3 \sin(t) - 2t \sin(t) + 2t^2 \cos(t) = 2t^2 \cos(t) - t^3 \sin(t) - 2t \sin(t) + 2t^2 \cos(t)$$

$$V_1' y_1 + V_2' y_2 = -t \sin(t) + \sin(t) 2t = t \sin(t)$$

$$y = C_1 t + C_2 t^2 + t \sin(t)$$

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$$y'' + 5y' + 6y = \cos e^t$$

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$$r^2 + 5r + 6 = 0$$

$$y_1 = e^{-2t}$$

$$y_2 = e^{-3t}$$

$$W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = \begin{vmatrix} e^{-2t} & e^{-3t} \\ -2e^{-2t} & -3e^{-3t} \end{vmatrix} = -3e^{-5t} + 2e^{-5t} = -e^{-5t}$$

$$V_1' = -\frac{y_2 f}{W} = \frac{e^{-3t} \cos e^t}{e^{-5t}} = e^{2t} \cos e^t$$

$$V_1 = \int e^{2t} \cos e^t dt = \left\{ \begin{array}{l} x = e^t \\ dx = e^t dt \end{array} \right\} = \int x^2 \cos x \frac{dx}{x} = \int x \cos x dx =$$

$$= x \sin x - \int \sin x dx = x \sin x + \cos x = e^t \sin e^t + \cos e^t$$

$$V_2' = \frac{y_1 f}{W} = \frac{e^{-2t} \cos e^t}{-e^{-5t}} = -e^{3t} \cos e^t$$

$$V_2 = -\int e^{3t} \cos e^t dt = -\int x^2 \cos x dx = -x^2 \sin x + \int 2x \sin x dx =$$

$$= -x^2 \sin x - 2x \cos x + \int 2 \cos x dx = -x^2 \sin x - 2x \cos x + 2 \sin x$$

$$y_p = V_1 y_1 + V_2 y_2 = (x \sin x + \cos x) \frac{1}{x^2} + (-x^2 \sin x - 2x \cos x + 2 \sin x) \frac{1}{x^3} =$$

$$= \frac{1}{x} \sin x + \frac{1}{x^2} \cos x - \frac{1}{x} \sin x - \frac{2}{x^2} \cos x + \frac{2}{x^3} \sin x = -\frac{1}{x^2} \cos x + \frac{2}{x^3} \sin x$$

$$y_p = -e^{-2t} \cos e^t + 2e^{-3t} \sin e^t$$